Linear Algebra and its Applications, Spring 2013 Suggested Solution for Final Exam

Instructor: Ling-Chieh Kung Department of Information Management National Taiwan University

1. (a) We have

| A = | $\begin{bmatrix} 1\\ 1 \end{bmatrix}$ | $\frac{2}{2}$ | $\frac{5}{4}$ | $\begin{array}{c} 1 \\ 0 \end{array}$ | $0 \\ -3$ | 4 4 | = | $\begin{bmatrix} 1\\ 1 \end{bmatrix}$ | $\begin{array}{c} 0 \\ 1 \end{array}$ | $\begin{array}{c} 0 \\ 0 \end{array}$ | $\begin{array}{c} 0\\ 0\\ \end{array}$ |][| $\begin{bmatrix} 1\\ 0 \end{bmatrix}$ | $\begin{array}{c} 2\\ 0 \end{array}$ | $5 \\ -1$ | $1 \\ -1$ | $\begin{array}{c} 0 \\ -3 \end{array}$ | $\frac{4}{0}$ | =LU. |
|-----|---------------------------------------|---------------|---|---------------------------------------|-----------|----------|---|---------------------------------------|---------------------------------------|---------------------------------------|--|----|---------------------------------------|--------------------------------------|---------------------------------------|---------------------------------------|--|---------------|------|
| | $\frac{3}{2}$ | $\frac{6}{4}$ | $\begin{array}{c} 14 \\ 10 \end{array}$ | 4 0 | -3 0 | 13 11 | | $\frac{3}{2}$ | $\begin{array}{c} 1 \\ 0 \end{array}$ | 1 -1 | 0 1 | | 0 0 | 0 0 | $\begin{array}{c} 0 \\ 0 \end{array}$ | $\begin{array}{c} 2 \\ 0 \end{array}$ | 0 0 | 1 4 | |

- (b) Because the column space is the entire \mathbb{R}^4 , the projection of any vector in \mathbb{R}^4 onto the column space is the same vector. Therefore, the projection of d is (3, 2, 4, 5).
- 2. (a) We have $\det A = \det(Q\Lambda Q^T) = \det Q \det \Lambda \det Q^T = \det \Lambda \det(Q^T Q) = \det \Lambda \det I = \det \Lambda$, which is exactly the product of A's eigenvalues.
 - (b) For *B*, first note that det $B = 24 \det B'$, where *B'* is a 4×4 matrix satisfying $B'_{ij} = 1$ if $i \neq j$ or 0 if i = j. For *B'*, note that three of its eigenvalues are -1, which then implies that the last eigenvalue is 3 (because the sum of eigenvalues are the trace, which is 0). Then we know that det B' = -3, the product of the eigenvalues. Collectively, det B = -72.
 - For *C*, which is a generalization of *B*, we follow the same way. First, det $C = n! \det C'$, where C' is an $n \times n$ matrix satisfying $C'_{ij} = 1$ if $i \neq j$ or 0 if i = j. For the eigenvalues of C', n-1 are -1 and one is n-1. Therefore, det $C' = (-1)^{n-1}(n-1)$ and thus det $C = (n!)(-1)^{n-1}(n-1)$.
- 3. (a) $u_1 = Au_0 = (0.2, 0.3, 0.5).$
 - (b) $u_2 = Au_1 = (0.29, 0.36, 0.35).$
 - (c) Because the sum of each column in A is 1 and all entries in A are no greater than 1, A is Markov. This implies that the process is neutrally stable.
 - (d) As eigenvectors corresponding to the eigenvalue 1 are $\{(5k, 6k, 5k)\}_{k \in \mathbb{R}}, u_{\infty} = (\frac{5}{16}, \frac{3}{8}, \frac{5}{16}).$
 - (e) The problem is not meaningful. Two points are given to you for free.
 - (f) The problem is not meaningful. Two points are given to you for free.
- 4. (a) False. A should be symmetric.
 - (b) False. When A's eigenvalues are all real, A may be asymmetric.
 - (c) False. The A in the next problem provides an example.
 - (d) True. A is unitary implies that A is normal, which then implies that A can have n independent eigenvectors of A.
 - (e) True. If A's eigenvalues are all positive, A is positive definite. Therefore, A can be decomposed into $A = R^T R$, where R has independent columns. As R has n columns, it must have n pivots.
- 5. We have

$$A = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{-1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} \sqrt{3} & 0 & 0 \\ 0 & \sqrt{7} & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{6}} & \frac{3}{\sqrt{14}} & \frac{-2}{\sqrt{21}} \\ \frac{-2}{\sqrt{6}} & \frac{2}{\sqrt{14}} & \frac{1}{\sqrt{21}} \\ \frac{1}{\sqrt{6}} & \frac{1}{\sqrt{14}} & \frac{4}{\sqrt{21}} \end{bmatrix}^T.$$

6. (a) Let x_1 and x_2 be eigenvector's of A associated with λ_1 and λ_2 , respectively. Then we have $\lambda_1 x_1^H x_2 = x_1^H A^H x_2 = x_1^H A x_2 = \lambda_2 x_1^H x_2$, where the second equality comes from the fact that A is positive semidefinite (and thus symmetric). Because $\lambda_1 \neq \lambda_2$, we have $x_1^H x_2 = 0$, i.e., x_1 and x_2 are orthogonal.

- (b) An lower bound is 0, because all eigenvalues must be nonnegative for A to be positive semidefinite.
- (c) Suppose μ is an eigenvalue of A kI, we have (A kI)x = μx, i.e., Ax = (μ + k)x. This implies that μ + k is an eigenvalue of A. Conversely, if λ is an eigenvalue of A, we have Ax = λx, which implies that (A kI)x = (λ k)x. We thus know that μ is an eigenvalue of A kI if and only if μ + k is an eigenvalue of A. Therefore, if the eigenvalues of A are λ₁, λ₂, ..., λ_n, the eigenvalues of A kI must be λ₁ k, λ₂ k, ..., λ_n k.
- (d) The statement is false, because a stationary point x must satisfy Ax = kx, which cannot be satisfied if k is not an eigenvalue of A.
- (e) A point (x, k) is a stationary point if and only if Ax = kx, which requires k to be an eigenvalue of A. For (x, k) to be a local minimum, we need A - kI, the Hessian matrix of f(x, k), to be positive semidefinite. This requires that all eigenvalues of A - kI to be nonnegative, and this happens if and only if k is the smallest eigenvalue of A. Therefore, there is a unique local minimum $(x_{\min}, \lambda_{\min}, \text{ where } \lambda_{\min} = \min_{i=1,\dots,n} \{\lambda_i \text{ and } x_{\min} \text{ is the associated eigenvector.} \}$
- 7. (a) An upper bound is $\binom{5}{2} = 10$.
 - (b) An upper bound is $\binom{6}{3} = 20$.
 - (c) There may be at most ten distinct bases. However, because columns 1 and 4 are dependent, x_1 and x_4 cannot form a basis. Similarly, x_2 and x_5 cannot form a basis. Therefore, there are eight distinct bases.
 - (d) The statement is false. For example, if n = m = 2 and the two equality constraints are $2x_1 + x_2 = 6$ and $x_1 + 2x_2 = 6$, there is only one basic solution (2, 2), which is also a basic feasible solution.
- 8. (a) The Hessian matrix is

$$A_2 = \left[\begin{array}{cc} 2r & -2 \\ -2 & 2r \end{array} \right].$$

- (b) For $\pi(p)$ to be strictly convex, we need A to be positive definite. This requires that $2r \ge 0$ and det $A_2 = 4r^2 - 4 \ge 0$, which together imply r > 1. Therefore, $\pi(p)$ is strictly convex if and only if r > 1.
- (c) The Hessian matrix is

$$A_3 = \left[\begin{array}{rrrr} 2r & -2 & -2 \\ -2 & 2r & -2 \\ -2 & -2 & 2r \end{array} \right].$$

- (d) For $\pi(p)$ to be strictly convex, we need A to be positive definite. To find a condition for positive definiteness, we calculate the eigenvalues of A_3 . Clearly if we can make all columns identical, there will be two eigenvalues associated with those identical columns. Therefore, two eigenvalues will be 2r + 2, which is always positive. The last eigenvalue can be found by 6r 2(2r + 2) = 2r 4 (the sum of eigenvalues is the trace) or recognizing that we may have an eigenvalue making the three columns sum to 0. It then follows that all we need is 2r 4 > 0, i.e., r > 2.
- (e) Similar to the case of n = 3, for a general n, there will be n 1 eigenvalues being 2r + 2. The last eigenvalue will be 2nr (n 1)(2r + 2) = 2r 2(n 1). The necessary and sufficient condition we need is r > n 1.