Operations Research, Spring 2016 Suggested Solution for Homework 3

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- 1. (a) The gradient and Hessian are $[3x^2 + 2ax + b]$ and [6x + 2a], respectively.
 - (b) When $x \ge -\frac{a}{3}$.
 - (c) When $x \leq -\frac{a}{3}$.
 - (d) An optimal solution is $x^* = \frac{-a \sqrt{a^2 3b}}{3}$. We let the $\nabla f(x^*)$ be 0. Notice that the result in Part (c) should be satisfied.

2. (a) We have
$$q^* = \sqrt{\frac{2KD}{h}}$$
 and $q' = \sqrt{\frac{KD}{h}}$.
(b) We have $\frac{q'}{q^*} = \sqrt{\frac{KD}{h}\frac{h}{2KD}} = \sqrt{\frac{1}{2}}$.

(c) We know
$$TC(q) = \frac{KD}{q} + \frac{hq}{2}$$
. Then $\frac{TC(q')}{TC(q*)} = \frac{\frac{3}{2}\sqrt{KDh}}{\sqrt{2KDH}} = \frac{3}{4}\sqrt{2}$.
(d) New q' becomes $\sqrt{\frac{2KkD}{h}}$ Then, we have $\frac{TC(q')}{TC(q*)} = \frac{\frac{\sqrt{2}}{2}\sqrt{KDh}(\frac{1}{\sqrt{k}}+\sqrt{k})}{\sqrt{2KDh}} = \frac{1}{2}\frac{k+1}{\sqrt{k}}$.

- 3. (a) The function is convex if $x_2 \ge 0$ and $-4x_1^2 \ge 0$. As the result, the function is convex over the region $x_1 = 0, x_2 \ge 0$.
 - (b) The function is nowhere convex.
 - (c) The function is convex if $x_2 \ge 0$, $2x_2x_3 x_1^2 \ge 0$, and $6x_2x_3^{-2} 4x_2^3 3x_1^2x_3^{-3} \ge 0$
 - (d) If n = 2 and 3, the Hessian matrix are

$$\nabla^2 f(x) = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$$
 and $\nabla^2 f(x) = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$

Follow the same rule, we know that no matter which number n is, $\nabla^2 f(x)$ is always positive semi-definite. Then, the function is convex everywhere.

4. (a) Let the decision variables be

 q_i = the sales quantity of product i, i = 1, 2, 3,

The seller's profit maximization problem is

$$\max \quad f(q) = \sum_{i=1}^{3} (a - bq_i - c)q_i$$

s.t.
$$\sum_{i=1}^{3} q_i \le K$$
$$q_i \ge 0 \quad \forall i = 1, 2, 3.$$

The Hessian matrix is

$$\nabla^2 f(q) = \left[\begin{array}{rrr} -2b & 0 & 0 \\ 0 & -2b & 0 \\ 0 & 0 & -2b \end{array} \right].$$

Since $\nabla^2 f(q)$ is always less than 0. It is a concave function. And the constraint is a linear function. As the result, it is a convex program.

- (b) The Lagrangian is $\mathcal{L}(q|\lambda) = \sum_{i=1}^{3} (a 2bq_i c)q_i + \lambda(K \sum_{i=1}^{3} q_i)$ $\frac{\partial \mathcal{L}(q|\lambda)}{\partial q_i} = a 2bq_i c \lambda \quad \forall i = 1, 2, 3$
 - The KKT condition for the problem is as follow $(\lambda \ge 0)$:
 - i. Primal feasibility: $\sum_{i=1}^{3} q_i \leq K$.
 - ii. Dual feasibility: $a 2bq_i c \lambda = 0$ $\forall i = 1, 2, 3.$ iii. Complementary slackness: $\lambda(K \sum_{i=1}^{3} q_i) = 0.$
- (c) By part(b), $q_i = \frac{a-c-\lambda}{2b}$ $\forall i = 1, 2, 3$. Because the constraint may be binding or nonbinding, there are two situation:
 - i. If the constraint is binding, then $q_1 + q_2 + q_3 = K$. As the result $q_1 = q_2 = q_3 = \frac{a c \lambda}{2b} = \frac{K}{3}$
 - ii. If the constraint is binding, then $q_i = \frac{a-c}{2b}$. Notice that the Lagrange multiplier λ is 0.

Combine the above result,
$$q^* = \min\{\frac{a-c}{2b}, \frac{\kappa}{3}\}$$
:

- i. $f(q^*) = aK \frac{bK^2}{3} cK$ when the constraint is binding.
- ii. $f(q^*) = \frac{(a-c)^2}{4b}$ when the constraint is nonbinding.
- (d) The optimal quantity $q_i^* = \min\{\frac{a-c}{2b}, \frac{K}{3}\}$. Therefore it (weakly) increases in a, decreases in b, and decreases in c when the constraint is nonbinding. If the constraint is binding, the increasing of K will make q_i^* larger. The intuitive explanations are as below:
 - i. For a, the reason is that the price is $a bq_i$, thus increasing of a makes the product more profitable. The seller will want to sell more products.
 - ii. For b, the reason is just the contrary of (i).
 - iii. For c, the reason is that it is unit production cost. The increasing of c means that producing the product becomes more expensive.
 - iv. For K, we know that $p_i c$ must be greater than 0, otherwise the seller will not sell the product. The increasing of K means that the total demand becomes larger. As the shadow price of demand constraint is positive, selling products must be more profitable.
- 5. (a) The gradient and Hessian are

$$abla f(x) = \begin{bmatrix} e^{x_1} \\ 2x_2 \end{bmatrix} \text{ and } \nabla^2 f(x) = \begin{bmatrix} e^{x_1} & 0 \\ 0 & 2 \end{bmatrix}.$$

(b) First, we set $x^0 = (2, 2)$ and the next solution be x^1 . We have

$$\nabla f(x^0) = \begin{bmatrix} e^2 \\ 4 \end{bmatrix}$$
 and $\nabla^2 f(x^0) = \begin{bmatrix} e^2 & 0 \\ 0 & 2 \end{bmatrix}$.

Therefore, we can obtain next solution by Newton's method:

$$x_1 = \begin{bmatrix} 2\\2 \end{bmatrix} - \begin{bmatrix} \frac{1}{e^2} & 0\\0 & \frac{1}{2} \end{bmatrix} \begin{bmatrix} e^2\\4 \end{bmatrix} = \begin{bmatrix} 1\\0 \end{bmatrix}.$$

(c) The first step is the same as (b). We have

$$\nabla f(x^0) = \left[\begin{array}{c} e^2 \\ 4 \end{array} \right].$$

Therefore, we can obtain next solution by the gradient descent method:

$$x_1 = \begin{bmatrix} 2\\2 \end{bmatrix} - 1 \begin{bmatrix} e^2\\4 \end{bmatrix} = \begin{bmatrix} 2-e^2\\-2 \end{bmatrix}.$$

(d) $a_0 = \operatorname{argmin}_{a>0} f(x^0 - a\nabla f(x^0)),$ where $f(x^0 - a\nabla f(x^0) = f(2 - ae^2, 2 - 4a) = e^{2-ae^2} + (2 - 4a)^2 = g(a)$. By FOC, $g'(a) = -e^{4-ae^2} - 8(2 - 4a) = 0$ when $a \approx 0.533$ Therefore, we can obtain next solution by the gradient descent method:

$$x_1 = \begin{bmatrix} 2\\2 \end{bmatrix} - 0.533 \begin{bmatrix} e^2\\4 \end{bmatrix} = \begin{bmatrix} 2 - 0.533e^2\\-0.132 \end{bmatrix}$$