# IM 1003: Programming Design Self-defined data types (in C)

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## **Self-defined data types**

- We can define data types by ourselves.
  - By **combining** data types into a composite type.
  - By **redefining** data types.
- We can always complete every program without self-defined data types.
  - But we can make our program **clearer** and more **flexible** by using them.
- In C, there are many ways of creating self-defined data types.
  - typedef, struct, union, and enum
  - We will introduce only the first two.
  - You can learn the other two by yourself (or ignore them at this moment).

## Outline

- struct
- typedef
- **struct** with member functions

### Example

- How to write a program to create two points *A* and *B* on the Cartesian coordinate system, compute vector *AB*, and print it out?
  - Let's implement a function that computes the vector.

```
int main()
{
    int x1 = 0, x2 = 0;
    int y1 = 10, y2 = 20;
    int rx = 0, ry = 0;
    vector (x1, y1, x2, y2, rx, ry);
    cout << rx << " " << ry << endl;
    return 0;
}</pre>
```

```
void vector(int x1, int y1, int x2,
    int y2, int& rx, int& ry)
{
    rx = x2 - x1;
    ry = y2 - y1;
}
```

– May we improve the program?

#### struct

- There are so many variables!
  - Some of them must be used in pairs.
- We want to **group** different data types into a single type.
  - Group **x** and **y** into a "point".
- In C, we do so by using **struct** (abbreviation of structure).
  - We may group basic data types, nonbasic data types (e.g., pointers and arrays), or even self-defined data types.
  - We do so when an item naturally consists of multiple **attributes**.
  - We do so to make the program easier to read and maintain.

### **Example with struct**

• Let's define a **new type Point**:

```
struct Point
{
    int x;
    int y;
};
```

- The keyword **struct** is used to define structures.
- Now it is a data type and we can use it to **declare variables**.

#### **Example with struct**

- With the new data type, the program can now be written in this way:
  - Declare variables with the selfdefined type name.
  - Assign values to both attributes by grouping values by curly brackets.
  - Access attributes through the dot operator.
- The function is also changed:
  - Use **Point** as a parameter type.
  - No need to call by reference.

```
Point vector (Point a, Point b)
  // Point as parameters
{
  Point vecXY;
  vecXY.x = B.x - A.x;
  vecXY.y = B.y - A.y;
  return vecXY; // return a Point
}
int main()
{
  Point a = \{0, 0\}, b = \{10, 20\};
  Point vecAB = vector (a, b);
  cout \ll vecAB.x \ll " ";
  cout \ll vecAB.y \ll endl;
  return 0;
}
```

### struct definition

- The syntax of defining a structure is:
  - A structure is typically named with the first letter capitalized.
  - An attribute/field can be of a basic data type, a nonbasic data type, or a selfdefined data type.
  - The number of attributes is unlimited.
  - All those semicolons are required.
- As another example, let's add one more attribute into **Point**:

struct struct name
{
type1 field 1;
type2 field 2;
type3 field 3;
// more fields
};



#### struct variable declaration

• To declare a variable defined as a structure, use

struct name variable name;

- Point A;
- Point B, C, thisIsAPoint;
- Point staticPointArray[10];
- Point\* pointPtr = &aPoint;
- Point\* dynamicPointArray = new Point[10];
- You may also (but usually people do not) write
  - struct Point A;
  - struct Point B, C, thisIsAPoint;

### Accessing struct attributes

• Use the dot operator "." to access a **struct** variable's attributes.

struct variable.attribute name

- An attribute is a single variable.
- We may do all the regular operations on an attribute.

```
Point a, b;
a.x = 0; // assignment
a.y = a.x + 10; // arithmetic
a.name = 'A';
cin >> b.name; // input
cout << a.x; // print out
b.y = a.y; // assignment
```

#### struct assignment

• We may use curly brackets to assign values to multiple attributes.

Point A = {0, 0, 'A'};
Point B;
B = {10, 20, 'B'};
C = {5, 0};
D = {2};

• **Partial assignments** are allowed (with unassigned attributes set to 0).

```
struct Point
{
  int x;
  int y;
  int z;
};
int main()
{
  Point A[100];
  for (int i = 0; i < 50; i++)
    A[i] = \{20\};
  for (int i = 0; i < 100; i++)
    cout \ll A[i].y \ll " " \ll A[i].z \ll endl;
  return 0;
}
```

#### struct and functions

- You may pass a **struct** variable as an argument into a function.
- You may return a **struct** variable from a function, too.
- Passing a struct variable by default is a call-by-value process.
- You may call by reference, as always.

```
struct Point
                              int main()
{
  int x;
                                Point a = \{10, 20\};
                                cout \ll a.x \ll " "
  int y;
};
                                      \ll a.y \ll endl;
void reflect (Point& a)
                                reflect (a);
                                cout \ll a.x \ll ""
{
  int temp = a.x;
                                      \ll a.y \ll endl;
                                return 0;
  a.x = a.y;
  a.y = temp;
                              }
}
```

#### Memory allocation for struct

- When we declare a structure variable, how does the compiler allocate memory spaces to it?
  - How many bytes are allocated in total?
  - Are attributes put together or separated?
  - What if we declare a structure array?

```
struct Point
{
  int x;
  int y;
};
int main()
{
  Point a[10];
  cout \ll sizeof (Point) \ll " " \ll sizeof (a) \ll endl;
  cout \ll \&a \ll endl;
  for (int i = 0; i < 10; i++)
    cout \ll \&a[i] \ll " " \ll \&a[i] .x \ll " " \ll \&a[i] .y \ll endl;
  Point* b = new Point[20];
  cout \ll sizeof (b) \ll endl;
  delete [] b;
  b = NULL;
  return 0;
}
```

## Outline

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#### typedef

- **typedef** is the abbreviation of "**type definition**".
- It allows us to create a new data type **from** another data type.
- To write a type definition statement:

#### typedef old type new type;

- This defines **new type** as **old type**.
  - **old type** must be an existing data type.
- So we do not really create any new type. Why do we do so?

#### Example

• Suppose we want to write a program that converts a given US dollar amount into an NT dollar amount.

```
double nt = 0;
double us = 0;
cin >> us;
nt = us * 29;
cout << nt << endl;</pre>
```

- Suppose in your program there are ten different kinds of monetary units, and you declared all of them to be **double**.
- What if one day you want to change all the types to **float**?

## Example with typedef

• To avoid modifying ten declaration statements, typedef helps!

```
typedef double Dollar; // define Dollar as double
Dollar nt; // declare a variable as Dollar
Dollar us;
cin >> us;
nt = us * 29;
cout << nt << endl;</pre>
```

- **Dollar** is a self-defined data type. It can be used to declare variables.
- If one day we want to change the type into float, int, etc., we only need to do one modification.
- Also, when one looks at your program, she will know that nt and us are "dollars" instead of just some double variables.

**"Type" life cycle** 

- You can put the **typedef** statement anywhere in the program.
  - At the beginning of the program, in the main function, inside a block, etc.
- The self-defined type can be used only **in the block** (if you declare it in any block).
- The same rule applies to **struct**.

## Example

- What may happen if we compile this program?
- How to fix it?
- Put the type definition statements and structure definition in the place that anyone can find it easily.
  - Usually it is the beginning of the program, just under the include statement.
- Put them globally unless you really use them locally.

```
int exchange (Dollar from, double rate);
int main()
{
   typedef double Dollar;
   Dollar NT, US;
   cin >> US;
   NT = exchange (US, 29);
   cout << NT << endl;
   return 0;
}
int exchange (Dollar from, double rate)
{
   return from * rate;
}</pre>
```

### typedef from struct

• Recall that we have done the following:

```
Point a = {0, 0};
Point b = {10, 20};
Point vecAB = vector (a, b);
```

- But **vecAB** is not a point! It is a vector.
- Vectors have the same attributes as points do. Should we define another structure that is identical to **Point**?
- We may combine **typedef** and **struct**.

// define Vector from Point
typedef Point Vector;

#### typedef from struct

• Suppose we do this:

```
struct Point
{
    int x;
    int y;
}; // end of struct definition
// define from struct
typedef Point Vector;
```

• Then we may write:

Point a(0, 0); Point b(10, 20); Vector vecAB = vector (a, b);

#### Example: <ctime>

- Many C++ standard library functionalities are provided with new types defined by typedef.
- As an example, the function clock(), defined in <ctime>, returns the number of system clock ticks elapsed since the execution of the program.
- What is **clock\_t**?

```
#include <iostream>
#include <ctime>
using namespace std;
int main()
{
    clock_t sTime = clock();
    for(int i = 0; i < 100000000; i++)
      ;
    clock_t eTime = clock();
    cout << sTime << " " << eTime << endl;
    return 0;
}</pre>
```

#### Example: <ctime>

- **clock()** returns a type **clock\_t** variable (for the number of ticks).
  - clock\_t is actually a long int. In <ctime>, there is a statement:

typedef long int clock\_t;

- So in our own functions, we may write clock\_t sTime = clock();.
  - We may change it to long int sTime = clock();.
- Why does the standard library do so?
- To print out the number of seconds instead of ticks:

cout << static\_cast<double>(eTime - sTime) / CLOCKS\_PER\_SEC << endl;

## Outline

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### Member variables

• Recall that we have defined

```
struct Point
{
    int x;
    int y;
};
```

- We say that **x** and **y** are the attributes or fields of the structure **Point**.
- They are also called the **member variables** of **Point**.
- Suppose we want to write a function that calculate a given point's distance from the origin. How may we do this?

## A global-function implementation

• We may write a function which takes a point as a parameter:

```
double distOri(Point p)
{
    double dist = sqrt(pow(p.x, 2) + pow(p.y, 2));
    return dist;
}
```

- We need to include **<cmath>**.
- This works, but this function is doing something that is related to **only one** point.
  - And it is calculating a **property** of the point.
- We may want to write this function as a part of **Point**.

## A member-function implementation

- We may redefine **Point** to include a **member function**:
  - distOri() is a member function of Point.
  - No argument is needed.
  - Who's x and y?
- To invoke a member function:

```
int main()
{
    Point a = {3, 4};
    cout << a.distOri();
    return 0;
}</pre>
```

```
struct Point
{
    int x;
    int y;
    double distOri()
    {
        double dist = sqrt(pow(x, 2) + pow(y, 2));
        return dist;
    }
};
```

#### A member-function implementation

• One may define a member function outside the **struct** statement.

- In fact this is typically preferred. Why?

#### The two ways of thinking

- What is the difference between the global-function and member-function implementations?
- The perspectives of looking at this functionality is different.
  - As a global function: I want to create a machine outside a point. Once I throw a point into it, I get the desired distance.
  - As a member function: I want to attach an operation on a point. Once I run this operation, I get the desired distance.
- The second perspective is preferred when we design more complicated items.
- The second way also enhances **modularity**.

## **Another example**

• Recall that we have written a **reflect** function:

```
struct Point
                              int main()
Ł
                                Point a = \{10, 20\};
  int x;
                                cout \ll a.x \ll ""
  int y;
};
                                      \ll a.y \ll endl;
void reflect (Point& a)
                                reflect (a);
                                cout \ll a.x \ll " "
{
  int temp = a.x;
                                      \ll a.y \ll endl;
                                return 0;
  a.x = a.y;
  a.y = temp;
                              }
```

• May we (should we) implement it as a member function?

## **Another example**

• A member-function implementation:

struct Point	int main()
{	{
int x;	Point $a = \{10, 20\};$
int y;	$cout \ll a.x \ll$ " "
<pre>void reflect();</pre>	$\ll$ a.y $\ll$ endl;
};	a.reflect();
<pre>void Point::reflect()</pre>	$cout \ll a.x \ll$ " "
{	$\ll$ a.y $\ll$ endl;
int temp = $x$ ;	return 0;
$\mathbf{x} = \mathbf{y};$	}
y = temp;	
}	

• Which one do you prefer?

#### **One common "error" for beginners**

• What is "wrong" in the following definition?

```
struct Point
{
    int x;
    int y;
    double distOri (Point p);
};
double Point::distOri (Point p)
{
    double dist = sqrt (pow (p.x, 2) + pow (p.y, 2));
    return dist;
}
```

• The program can still run. However, never do this!

## **One common "error" for beginners**

• How about this?

```
struct Point
{
    int x;
    int y;
    void reflect (Point& p);
};
void Point::reflect(Point& p)
{
    int temp = p.x;
    p.x = p.y;
    p.y = temp;
}
```