# Systems Modeling (Based on [Clarke *et al.* 1999])

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#### Introduction

- First two steps in correctness verification:
  - 1. Specify the desired *properties*
  - 2. Construct a *formal model* (with the desired properties in mind)
    - Capture the necessary properties and leave out the irrelevant
    - Example: gates and boolean values vs. voltage levels
    - Example: exchange of messages vs. contents of messages
- Description of a formal model
  - Graphs
  - Logic formulae



#### **Concurrent Reactive Systems**

- Interact frequently with the environment and may not terminate
- Temporal (not just input-output) behaviors are most important
- Modeling elements:
  - State: a snapshot of the system at a particular instance
  - Transition:
    - how the system changes its state as a result of some action
    - described by a pair of the state before and the state after the action
  - Computation: an infinite sequence of states resulted from transitions

#### Kripke Structures

- Kripke structures are one of the most popular types of formal models for concurrent systems.
- Let AP be a set of atomic propositions (representing things you want to observe).
- A Kripke structure M over AP is a tuple  $\langle S, S_0, R, L \rangle$ :
  - $\clubsuit$  S is a finite set of states,
  - $S_0 \subseteq S$  is the set of initial states,
  - $R \subseteq S \times S$  is a *total* transition relation, and
  - \*  $L: S \to 2^{AP}$  is a function labeling each state with a subset of propositions (which are true in that state).
- A computation or path of M from a state s is an infinite sequence of states  $\sigma = s_0, s_1, s_2, \cdots$  such that  $s_0 = s$  and  $(s_i, s_{i+1}) \in R$ , for all  $i \ge 0$ .

#### First-Order Representations

- First-order formulae serve as a unifying formalism for describing concurrent systems.
- Elements of first-order logic:
  - Logical connectives (∧, ∨, ¬, →, etc.) and quantifiers
     (∀ and ∃)
  - Predicate and function symbols (with predefined meanings)
- Variables range over a finite domain D.
- $\bullet$  A *valuation* for a set V of variables is a map from the variables in V to the values in the domain D.
- A state of a system is a valuation for the system variables.
  - A set of states can be described by a first-order formula.

# First-Order Representations (cont.)

- The set of initial states of a system will typically be described by  $S_0(V)$ .
- To describe transitions by logic formulae, we create a second copy of variables V'.
- $\bullet$  Each variables v in V has a corresponding primed version v' in V'.
- The variables in V are present state variables, while the variables in V' are next state variables.
- $\bullet$  A valuation for V and V' can be seen as designating a pair of states or a transition.
- A set of transitions or transition relation R can then be described by a first-order formula  $\mathcal{R}(V,V')$ .



# From Formulae to Kripke Structures

- Given  $S_0(V)$  and R(V,V') that represent a concurrent system, a Kripke structure  $M = \langle S, S_0, R, L \rangle$  may be derived:
  - $\circledast$  S is the set of all valuations for V.
  - \* The set of initial states  $S_0$  is the set of all valuations for V satisfying  $S_0$ .
  - \*\* R(s,s') holds if  $\mathcal{R}$  evaluates to true when each  $v \in V$  is assigned the value s(v) and each  $v' \in V'$  is assigned the value s'(v).
  - \* L is defined such that L(s) is the set of atomic propositions true in s.
- To make R total, for every state s that does not have a successor, (s,s) is added into R.

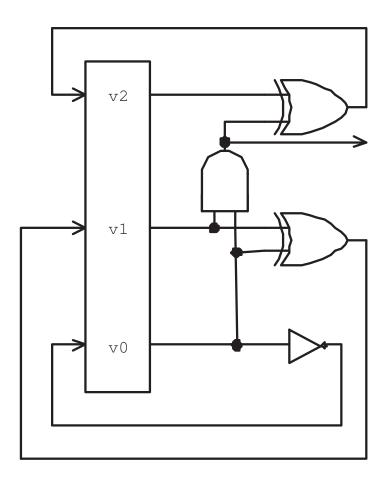


#### Varieties of Concurrent Systems

- A concurrent system consists of a set of components that execute together.
- Modes of execution:
  - Asynchronous
  - Synchronous
- Modes of communication:
  - Shared variables
  - Message-passing
  - Handshaking (or joint events)



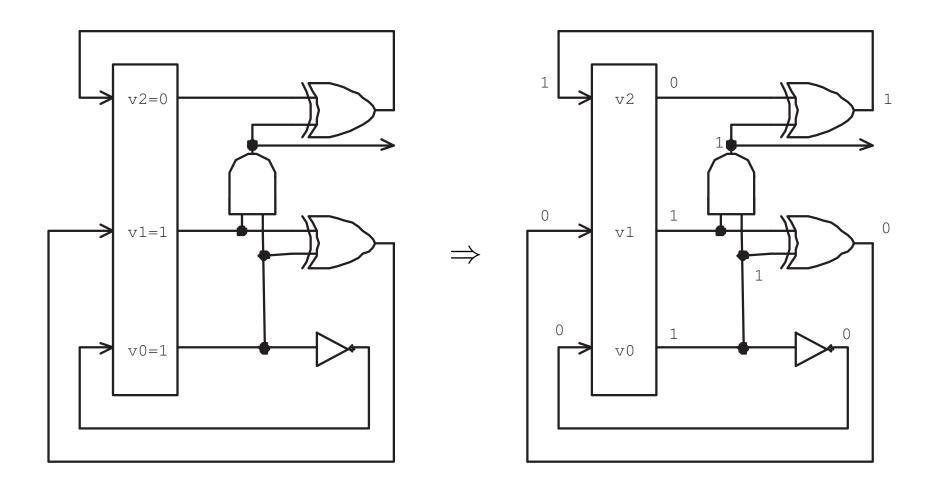
#### A Synchronous Modulo 8 Counter



Source: redrawn from [Clarke et al. 1999, Fig 2.1]



# A Synchronous Modulo 8 Counter (cont.)





# First-Order Representations (Circuit)

- Let V be  $\{v_0, v_1, v_2\}$ .
- The transitions of the modulo 8 counter are

$$v_0' = \neg v_0$$

$$v_1' = v_0 \oplus v_1$$

$$v_2' = (v_0 \wedge v_1) \oplus v_2$$

In terms of formulae, they are

$$\circledast \mathcal{R}_1(V, V') \stackrel{\Delta}{=} v_1' \Leftrightarrow v_0 \oplus v_1$$

$$\stackrel{*}{\circledast} \mathcal{R}_2(V, V') \stackrel{\Delta}{=} v_2' \Leftrightarrow (v_0 \land v_1) \oplus v_2$$

Conjoining the formulae, we obtain



#### **Programs**

- Concurrent programs are composed of sequential programs/statements.
- A sequential program consists of statements sequentially composed with each other.
- We assume that all statements of a program have a unique entry point and a unique exit point (they are structured).
- To obtain a first-order representation of a program, it is convenient to *label* each statement of the program.



# Labeling a Sequential Statement

- Given a sequential statement P, the labeled statement  $P^L$  is defined as follows, assuming all labels are unique:
  - $\clubsuit$  If P is not composite, then  $P^L = P$ .
  - **!** If  $P = P_1; P_2$ , then  $P^L = P_1^L; l : P_2^L$ .
  - \* If  $P = \mathbf{if} \ b \ \mathbf{then} \ P_1 \ \mathbf{else} \ P_2 \ \mathbf{fi}$ , then  $P^L = \mathbf{if} \ b \ \mathbf{then} \ l_1 : P_1^L \ \mathbf{else} \ l_2 : P_2^L \ \mathbf{fi}$ .
  - \* If P =while b do  $P_1$  od, then  $P^L =$ while b do  $l_1 : P_1^L$  od.
- The above labeling procedure may be extended to treat other statement types.



# First-Order Representations (Sequential)

- Consider a labeled program P, with the entry labeled m and exit labeled m'.
- Let V denote the set of program variables.
- We postulate a special variable pc called the *program* counter that ranges over the set of program labels plus the *undefined value*  $\bot$  (bottom).
- Let same(Y) abbreviate  $\bigwedge_{y \in Y} (y' = y)$ .

$$S_0(V, pc) \stackrel{\Delta}{=} pre(V) \wedge pc = m.$$



# First-Order Representations (cont.)

The transition relation C(l, P, l') for a statement P with entry l and exit l' is defined recursively as follows:

Assignment:

$$C(l, v := e, l') \stackrel{\Delta}{=} pc = l \land pc' = l' \land v' = e \land same(V \setminus \{v\}).$$

Skip:

$$C(l, skip, l') \stackrel{\Delta}{=} pc = l \wedge pc' = l' \wedge same(V)$$
.

Sequential Composition:

$$C(l, P_1; l'': P_2, l') \stackrel{\Delta}{=} C(l, P_1, l'') \vee C(l'', P_2, l').$$



# First-Order Representations (cont.)

Conditional:

 $C(l, \mathbf{if}\ b\ \mathbf{then}\ l_1: P_1\ \mathbf{else}\ l_2: P_2\ \mathbf{fi}, l')$  is the disjunction of the following:

- $pc = l \wedge pc' = l_1 \wedge b \wedge same(V)$
- $pc = l \wedge pc' = l_2 \wedge \neg b \wedge same(V)$
- $C(l_1, P_1, l')$
- $C(l_2, P_2, l')$
- While:

 $C(l, \mathbf{while}\ b\ \mathbf{do}\ l_1: P_1\ \mathbf{od}, l')$  is the disjunction of the following:

- $pc = l \wedge pc' = l_1 \wedge b \wedge same(V)$
- $pc = l \land pc' = l' \land \neg b \land same(V)$
- $C(l_1, P_1, l)$



#### **Concurrent Programs**

- Concurrent programs are composed of sequential processes (programs/statements).
- We consider only asynchronous concurrent programs, where exactly one process can make a transition at any time.
- A concurrent program P has the following form:

cobegin 
$$P_1 \parallel P_2 \parallel \cdots \parallel P_n$$
 coend

where  $P_i$ 's are processes.

- Let V be the set of all program variables and  $V_i$  the set of variables that can be changed by  $P_i$ .
- Let pc be the program counter of P and  $pc_i$  that of  $P_i$ ; let PC be the set of all program counters.

# **Labeling Concurrent Programs**

• Given  $P = \text{cobegin } P_1 \parallel P_2 \parallel \cdots \parallel P_n \text{ coend, then}$   $P^L = \text{cobegin } l_1 : P_1^L \ l_1' \ \parallel \ l_2 : P_2^L \ l_2' \ \parallel \cdots \ \parallel \ l_n : P_n^L \ l_n' \text{ coend.}$ 

 $\bullet$  Note that each process  $P_i$  has a unique exit label  $l'_i$ .



#### First-Order Representations (Concurrent)

- igoplus Assume the entry is labeled m and exit labeled m'.
- Given some condition pre(V) on the initial values, the set of initial states is

$$S_0(V, PC) \stackrel{\Delta}{=} pre(V) \land pc = m \land \bigwedge_{i=1}^n (pc_i = \bot)$$

where  $pc_i = \bot$  indicates that  $P_i$  is *not active*.

•  $C(l, \mathbf{cobegin}\ l_1 : P_1\ l'_1\ \|\ l_1 : P_2\ l'_2\ \| \cdots \|\ l_n : P_n\ l'_n\ \mathbf{coend}, l')$  is the disjunction of the following:

$$pc = l \wedge pc'_1 = l_1 \wedge \cdots \wedge pc'_n = l_n \wedge pc' = \bot$$
 (initialization)

\*\* 
$$pc = \bot \land pc_1 = l'_1 \land \cdots \land pc_n = l'_n \land pc' = l' \land_{i=1}^n (pc'_i = \bot)$$
 (termination)

 $\bigvee_{i=1}^{n} (C(l_i, P_i, l_i') \land same(V \setminus V_i) \land same(PC \setminus \{pc_i\})$  (interleaving)

#### **Synchronization Statements**

- igoplus Assume the statement belongs to  $P_i$ .
- Wait (or await):

 $C(l, \mathbf{wait}(b), l')$  is the disjunction of the following:

$$pc_i = l \land pc'_i = l \land \neg b \land same(V_i)$$

$$pc_i = l \wedge pc'_i = l' \wedge b \wedge same(V_i)$$

• Lock (or test-and-set):  $C(l, \mathbf{lock}(v), l')$  is the disjunction of the following:

$$pc_i = l \wedge pc_i' = l \wedge v = 1 \wedge same(V_i)$$

$$pc_i = l \wedge pc_i' = l' \wedge v = 0 \wedge v' = 1 \wedge same(V_i \setminus \{v\})$$

Unlock:

$$C(l, \mathbf{unlock}(v), l') \stackrel{\Delta}{=} pc_i = l \wedge pc'_i = l' \wedge v' = 0 \wedge same(V_i \setminus \{v\}).$$



#### **A Mutual Exclusion Program**

$$P_{MX} = m : \mathbf{cobegin} \ P_0 \parallel P_1 \ \mathbf{coend} \ m'$$

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P_0 = P_1 = l_0 : \mathbf{while} \ true \ \mathbf{do} \ NC_0 : \mathbf{wait} \ T = 0; \ CR_0 : T := 1; \ CR_1 : T := 0; \ \mathbf{od}; \ l_1'
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- $V = V_0 = V_1 = \{T\}; PC = \{pc, pc_0, pc_1\}.$
- The pc of  $P_{MX}$  may take m,  $\perp$ , or m'.
- $\bullet$  The  $pc_0$  of  $P_0$ :  $\bot$ ,  $l_0$ ,  $NC_0$ ,  $CR_0$ , or  $l'_0$ .
  - The  $pc_1$  of  $P_1$ :  $\perp$ ,  $l_1$ ,  $NC_1$ ,  $CR_1$ , or  $l'_1$ .

# First-Order Representation of $P_{MX}$

- Initial states  $S_0(V, PC)$ :  $pc = m \land pc_0 = \bot \land pc_1 = \bot$ .
- Transition relation  $\mathcal{R}(V, PC, V', PC')$  is the disjunction of

$$pc = m \wedge pc'_0 = l_0 \wedge pc'_1 = l_1 \wedge pc' = \bot$$

$$pc_0 = l'_0 \land pc_1 = l'_1 \land pc' = m' \land pc'_0 = \bot \land pc'_1 = \bot$$

$$\ref{eq:constraints} C(l_0, P_0, l_0') \wedge same(V \setminus V_0) \wedge same(PC \setminus \{pc_0\})$$

$$\ref{eq:constraints} C(l_1, P_1, l_1') \wedge same(V \setminus V_1) \wedge same(PC \setminus \{pc_1\})$$

• For each  $P_i$ ,  $C(l_i, P_i, l'_i)$  is the disjunction of

$$pc_i = l_i \land pc'_i = NC_i \land true \land same(T)$$

$$pc_i = NC_i \wedge pc'_i = CR_i \wedge T = i \wedge same(T)$$

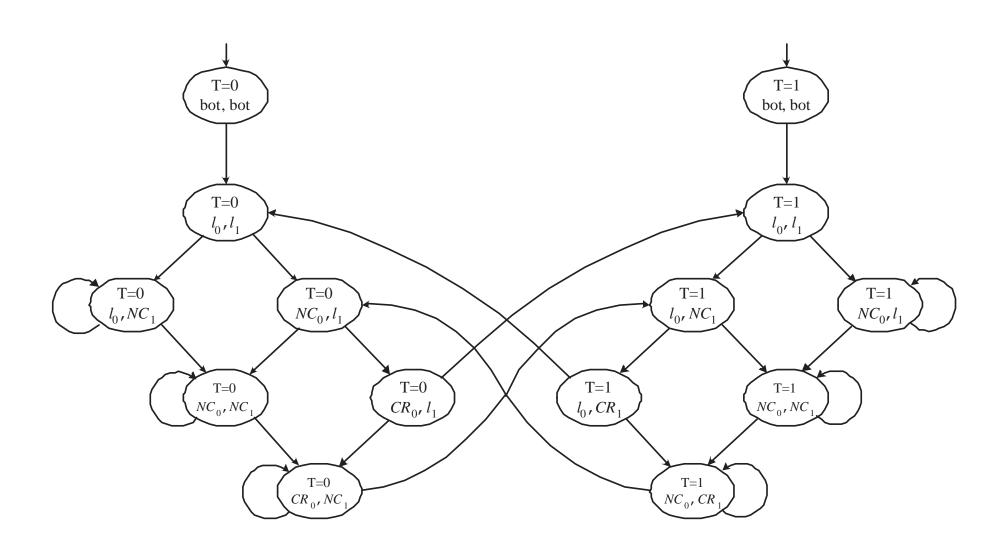
$$pc_i = CR_i \wedge pc_i' = l_i \wedge T = (1-i)$$

$$pc_i = NC_i \land pc'_i = NC_i \land T \neq i \land same(T)$$

$$pc_i = l_i \wedge pc'_i = l'_i \wedge false \wedge same(T)$$



# A Kripke Structure for $P_{MX}$



Source: redrawn from [Clarke et al. 1999, Fig 2.2]

