

Reduction (Based on [Manber 1989])

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Reduction

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Introduction



- The basic idea of *reduction* is to solve a problem with the solution to another "similar" problem.
- When Problem A can be reduced to Problem B, there are two consequences:
 - A solution to Problem B may be used to solve Problem A.
 If A is known to be "hard", then B is also necessarily "hard".
- One should avoid the pitfall of reducing a problem to another that is too general or too hard.

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Matching



- Given an undirected graph G = (V, E), a matching is a set of edges that do not share a common vertex.
- A maximum matching is one with the maximum number of edges.
- A maximal matching is one that cannot be extended by adding any other edge.

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Bipartite Matching



- A bipartite graph G = (V, E, U) is a graph with $V \cup U$ as the set of vertices and E as the set of edges such that
 - 🌻 V and U are disjoint and
 - $\overset{\circ}{=}$ The edges in E connect vertices from V to vertices in U.

Problem

Given a bipartite graph G = (V, E, U), find a maximum matching in G.

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Networks



- So Consider a directed graph, or network, G = (V, E) with two distinguished vertices: s (the source) with indegree 0 and t (the sink) with outdegree 0.
- Each edge e in E has an associated positive weight c(e), called the capacity of e.

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• A **flow** is a function *f* on *E* that satisfies the following two conditions:

1.
$$0 \le f(e) \le c(e)$$
.
2. $\sum_{u} f(u, v) = \sum_{w} f(v, w)$, for all $v \in V - \{s, t\}$.

The network flow problem is to maximize the flow f for a given network G.

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Bipartite Matching to Network Flow



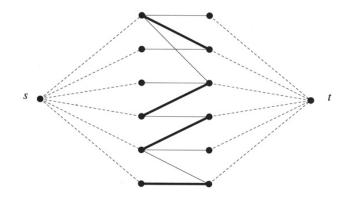


Figure 7.39 Reducing bipartite matching to network flow (the directions of all the edges are from left to right).

Source: [Manber 1989].

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Bipartite Matching to Network Flow (cont.)



Mapping from the input G = (V, E, U) of the bipartite matching problem to the input G' = (V', E') and c of the network flow problem:

$$𝔅 V' = {s} ∪ V ∪ U ∪ {t} 𝔅 E' = {(s, v) | v ∈ V} ∪ E ∪ {(u, t) | u ∈ U}$$

otin The capacity for every $e\in E'$ is 1, i.e., $orall e\in E', c(e)=1.$

- Correspondence between the two solutions
 - Solution A maximum flow f in G' defines a maximum matching M_f in G.
 - A maximum matching M in G induces a maximum flow f_M in G'.

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Notations



- Let \overline{v} denote a vector (v_1, v_2, \dots, v_n) of *n* constants or *n* variables.
- So In the following, \overline{a} , \overline{b} , \overline{c} , and \overline{e} are vectors of *n* constants.
- And, \overline{x} and \overline{y} are vectors of *n* variables.
- The (inner or dot) product a · x of two vectors a and x is defined as follows:

$$\overline{a} \cdot \overline{x} = \sum_{i=1}^{n} a_i \cdot x_i$$

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Linear Programming



Objective function:

 $\overline{c} \cdot \overline{x}$

Sequality constraints:

$$\left[egin{array}{c} \overline{e}_1 \ \overline{e}_2 \ dots \ \overline{e}_m \end{array}
ight] \overline{x} = \left[egin{array}{c} d_1 \ d_2 \ dots \ dots \ d_m \end{array}
ight]$$

- Inequality constraints may be turned into equality constraints by introducing *slack* variables.
- The goal is to maximize (or minimize) the value of the objective function, subject to the equality constraints.

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Network Flow to Linear Programming



- Mapping from the input G = (V, E) and c of the network flow problem to the objective function and constraints of linear programming:
 - Et x_1, x_2, \ldots, x_n represent the flow of the *n* edges.
 - Objective function

$$\sum_{i\in S} x_i$$

where S is the set of edges leaving the source. Inequality constraints

$$x_i \leq c_i$$
, for all $i, 1 \leq i \leq n$

where c_i is the capacity of edge *i*.

Equality constraints

$$\sum_{i \text{ leaves } v} x_i - \sum_{j \text{ enters } v} x_j = 0, \text{ for every } v \in V \setminus \{s, t\}$$

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