

# Reduction (Based on [Manber 1989])

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#### Introduction



- The basic idea of *reduction* is to solve a problem with the solution to another "similar" problem.
- When Problem A can be reduced (efficiently) to Problem B, there are two consequences:
  - A solution to Problem B may be used to solve Problem A.
     If A is known to be "hard", then B is also necessarily "hard".
- One should avoid the pitfall of reducing a problem to another that is too general or too hard.

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### Matching



- Given an undirected graph G = (V, E), a matching is a set of edges that do not share a common vertex.
- A maximum matching is one with the maximum number of edges.
- A maximal matching is one that cannot be extended by adding any other edge.

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#### **Bipartite Matching**



- A bipartite graph G = (V, E, U) is a graph with  $V \cup U$  as the set of vertices and E as the set of edges such that
  - 🌻 V and U are disjoint and
  - $\overset{\circ}{=}$  The edges in E connect vertices from V to vertices in U.

#### Problem

Given a bipartite graph G = (V, E, U), find a maximum matching in G.

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### Bipartite Matching (cont.)



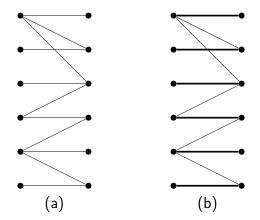


Figure: A bipartite graph and a maximum matching. Source: adapted from [Manber 1989, Figure 7.37].

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### Bipartite Matching (cont.)



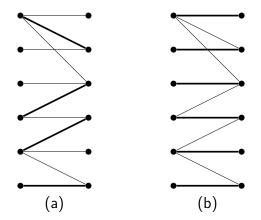


Figure: A maximal matching and a maximum matching. Source: adapted from [Manber 1989, Figure 7.37].

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#### Networks



- Solution Consider a directed graph, or network, G = (V, E) with two distinguished vertices: s (the source) with indegree 0 and t (the sink) with outdegree 0.
- Each edge e in E has an associated positive weight c(e), called the capacity of e.

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• A **flow** is a function *f* on *E* that satisfies the following two conditions:

1. 
$$0 \le f(e) \le c(e)$$
.  
2.  $\sum_{u} f(u, v) = \sum_{w} f(v, w)$ , for all  $v \in V - \{s, t\}$ .

The network flow problem is to maximize the flow f for a given network G.

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#### **Bipartite Matching to Network Flow**



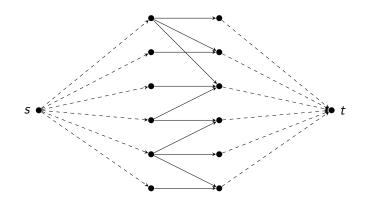


Figure: Reducing bipartite matching to network flow. Every edge has capacity 1.

Source: redrawn from [Manber 1989, Figure 7.39].

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### Bipartite Matching to Network Flow (cont.)



Mapping from the input G = (V, E, U) of the bipartite matching problem to the input G' = (V', E') and c of the network flow problem:

$$𝔅 V' = {s} ∪ V ∪ U ∪ {t} 𝔅 E' = {(s, v) | v ∈ V} ∪ E ∪ {(u, t) | u ∈ U}$$

otin The capacity for every  $e\in E'$  is 1, i.e.,  $orall e\in E', c(e)=1.$ 

- Correspondence between the two solutions
  - Solution A maximum flow f in G' defines a maximum matching  $M_f$  in G.
  - A maximum matching M in G induces a maximum flow  $f_M$  in G'.

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#### Notations



- Let  $\overline{v}$  denote a vector  $(v_1, v_2, \dots, v_n)$  of *n* constants or *n* variables.
- So In the following,  $\overline{a}$ ,  $\overline{b}$ ,  $\overline{c}$ , and  $\overline{e}$  are vectors of *n* constants.
- And,  $\overline{x}$  and  $\overline{y}$  are vectors of *n* variables.
- The (inner or dot) product a · x of two vectors a and x is defined as follows:

$$\overline{a} \cdot \overline{x} = \sum_{i=1}^{n} a_i \cdot x_i$$

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## **Linear Programming**

😚 Objective function:



 $\overline{c} \cdot \overline{x}$ 

Sequality constraints:

$$\overline{e}_1 \cdot \overline{x} = d_1 \overline{e}_2 \cdot \overline{x} = d_2 \vdots \overline{e}_m \cdot \overline{x} = d_m$$

- Inequality constraints may be turned into equality constraints by introducing *slack* variables.
- Non-negative constraints: x<sub>j</sub> ≥ 0, for all j in P, where P is a subset of {1, 2, ..., n}.
- The goal is to maximize (or minimize) the value of the objective function, subject to the equality constraints.

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### Network Flow to Linear Programming



- From the input G = (V, E) and c of the network flow problem to the objective function and constraints of linear programming:
  - Let  $x_1, x_2, \ldots, x_n$  represent the flow values of the *n* edges.
  - Objective function:

$$\sum_{i\in S} x_i$$

where S is the set of edges leaving the source.

Inequality constraints:

 $x_i \leq c_i$ , for all  $i, 1 \leq i \leq n$ 

where  $c_i$  is the capacity of edge i.

Equality constraints:

$$\sum_{i \text{ leaves } v} x_i - \sum_{j \text{ enters } v} x_j = 0, \text{ for every } v \in V \setminus \{s, t\}$$

Non-negative constraints:  $x_i \ge 0$ , for all  $i, 1 \le i \le n$ .

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