

Bounded Model Checking (Based on [Biere et al. 1999, Benedetti and Cimatti 2003])

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Outline



📀 Introduction

- 📀 An Illustrative Example
- Part I: Bounded Model Checking for LTL (with future only)
- Part II: Bounded Model Checking for LTL with Past (or Full PTL)

😚 References:

[Biere *et al.*] A. Biere, A. Cimatti, E. Clarke, and Y. Zhu, "Symbolic Model Checking without BDD," *TACAS 1999*, *LNCS1579*.

[Benedetti and Cimatti] M. Benedetti and A. Cimatti, "Bounded Model Checking for Past LTL," *TACAS 2003, LNCS 2619.*

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Introduction



- In symbolic model checking, BDDs had traditionally been used for boolean encodings.
- 📀 Drawbacks of BDDs:
 - For large systems (with over a few hundred boolean variables), they can be prohibitively large.
 - Selecting the right variable ordering is often time-consuming or needs manual intervention.
- Propositional decision procedures, or SAT solvers, also operate on boolean expressions, but do not use canonical forms.
- SAT solvers can handle thousands of variables or even more.

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Introduction (cont.)



Basic ideas of bounded model checking (BMC):

- Solutions k Consider counterexamples of a particular length k.
- Generate a propositional formula that is satisfiable iff such a counterexample exists.
- The propositional formula can be tested for satisfiability by a SAT solver.
- S Advantages of BMC:
 - It finds counterexamples very fast.
 - It finds counterexamples of minimal length.
 - It uses much less space than BDD-based approaches.
 - It does not need a manually selected variable ordering or time-consuming dynamic reordering.

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An Example



- 📀 Consider a three-bit shift register.
- Let $M = \langle X, I, T \rangle$ be its state machine:
 - ***** $X \triangleq \{x[0], x[1], x[2]\}$ contains the three bits.
 - I(X) ≜ true, posing no restriction on the initial states.
 - $= \overline{T}(X,X') \triangleq (x'[0] \Leftrightarrow x[1]) \land (x'[1] \Leftrightarrow x[2]) \land x'[2].$
- Suppose we want to check if eventually all three bits are set to 0, i.e., if LTL formula p ≜ ◊(¬x[0] ∧ ¬x[1] ∧ ¬x[2]) holds on all paths in M.
- To do so, we search for a path in M such that $\neg p \triangleq \Box(x[0] \lor x[1] \lor x[2])$ on the path.
- If we succeed, then p does not hold on all paths; otherwise, it does.

An Example (cont.)



- We look for (looping) paths with at most k + 1 states, for instance k = 2.
- Solution Let X_i denote the set $\{x_i[0], x_i[1], x_i[2]\}$.
- The first 3 states of such a path can be characterized by the following boolean formula:

$$f_{\mathcal{M}} \triangleq I(X_0) \land T(X_0, X_1) \land T(X_1, X_2)$$

A witness for ¬p must contain a loop from X₂ back to X₀, X₁, or X₂:

$$L_i \triangleq T(X_2, X_i)$$

The path must fulfill the constraints imposed by $\neg p$:

$$S_i \triangleq x_i[0] \lor x_i[1] \lor x_i[2]$$

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An Example (cont.)



The following formula is satisfiable iff there is a counterexample of length 2 for p.

$$f_M \wedge \bigvee_{i=0}^2 L_i \wedge \bigwedge_{i=0}^2 S_i$$

Itere is a satisfying assignment:

$$\begin{array}{rl} x_0[0] = x_0[1] = x_0[2] \\ = & x_1[0] = x_1[1] = x_1[2] \\ = & x_2[0] = x_2[1] = x_2[2] \\ = & 1. \end{array}$$

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Part I:

Bounded Model Checking for LTL

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Kripke Structures



• A Kripke structure is a tuple M = (S, I, T, L) with

- $\stackrel{\scriptstyle \bullet}{=}$ a finite set of states S,
- otin the set of initial states $I\subseteq S$,
- onumber s a transition relation between states $\mathcal{T} \subseteq \mathcal{S} imes \mathcal{S}$, and
- the labeling of the states $L : S \to \mathscr{P}(A)$ with atomic propositions A.
- S Every state of *M* is required to have a successor.
- 📀 We write s
 ightarrow t for $(s,t) \in {\mathcal T}$.
- 📀 For an infinite sequence π of states s_0, s_1, \ldots , we define

• An infinite sequence π is a path if $\pi(i) \to \pi(i+1)$ for all $i \in \mathbb{N}$.

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Linear Temporal Logic (LTL)



- Let M be a Kripke structure, π be a path in M, and f be an LTL formula (in negation normal form).
- $\pi \models f$ (f is valid along π) is defined as follows:

$$\begin{aligned} \pi &\models p & \text{iff} \quad p \in L(\pi(0)) \\ \pi &\models \neg p & \text{iff} \quad p \notin L(\pi(0)) \\ \pi &\models f \land g & \text{iff} \quad \pi \models f \text{ and } \pi \models g \\ \pi &\models f \lor g & \text{iff} \quad \pi \models f \text{ or } \pi \models g \\ \pi &\models \Box f & \text{iff} \quad \forall j \in [0, \infty) . \pi^j \models f \\ \pi &\models \Diamond f & \text{iff} \quad \exists j \in [0, \infty) . \pi^j \models f \\ \pi &\models \bigcirc f & \text{iff} \quad \pi^1 \models f \\ \pi &\models f \mathcal{U} g & \text{iff} \quad \exists j \in [0, \infty) . (\pi^j \models g \text{ and } \forall k \in [0, j) . \pi^k \models f) \\ \pi &\models f \mathcal{R} g & \text{iff} \quad \forall j \in [0, \infty) . (\pi^j \models g \text{ or } \exists k \in [0, j) . \pi^k \models f) \end{aligned}$$

Model Checking



- An LTL formula f is valid in a Kripke structure M, denoted as $M \models \mathbf{A} f$, iff $\pi \models f$ for all paths π in M with $\pi(0) \in I$.
- Or An LTL formula *f* is satisfiable in a Kripke structure *M*, denoted as *M* ⊨ **E** *f*, iff there is a path π in *M* such that $\pi \models f$ and $\pi(0) \in I$.
- Given a Kripke structure M and an LTL formula f, the model checking problem is to determine whether $M \models \mathbf{A} f$, which is equivalent to determine whether $M \not\models \mathbf{E} \neg f$.
- In the following, the problem is restricted to find a witness for formulae of the form E f.

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Bounded Model Checking



- Consider only a finite prefix of a path that may be a witness of E f.
- We restrict the length of the prefix to a certain bound *k*.
- Generate a propositional formula that is satisfiable iff there is a witness within the bound k.
- The propositional formula can be solved by a SAT solver.
- If there is no witness within bound k, we increase the bound and look for longer and longer possible witnesses.

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Infinite Paths from the Prefix

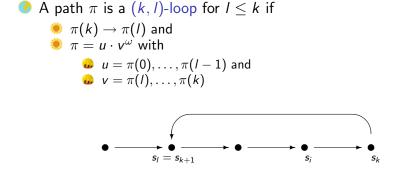


- Though the prefix of a path is finite, it still might represent an infinite path if there is a back loop from the last state of the prefix to any of the previous states.
- If there is no such back loop, then the prefix does not say anything about the infinite behavior of the path.
- Solution Only a prefix with a back loop can represent a witness for $\Box f$.

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Loops





A path π is a k-loop if there is an l ∈ N with l ≤ k for which π is a (k, l)-loop.

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- In bounded semantics, we only consider a finite prefix of a path which may or may not be a loop.
- In particular, we only use the first k + 1 states of a path to determine the validity of a formula along that path.
- The bounded semantics $\pi \models_k f$ states that the LTL formula f is valid along the path π with bound k.

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Bounded Semantics for a Loop



- Let $k \in \mathbb{N}$ and π be a k-loop.
- $\bigcirc \pi \models_k f \text{ iff } \pi \models f.$
- This is so, because all information about π is contained in the prefix of length k.

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Bounded Semantics without a Loop



• Let
$$k \in \mathbb{N}$$
 and π be a path that is not a k -loop.
• $\pi \models_k f$ iff $(\pi, 0) \models_k f$ where

$$\begin{array}{lll} (\pi,i) \models_{k} p & \text{iff} & p \in L(\pi(i)) \\ (\pi,i) \models_{k} \neg p & \text{iff} & p \notin L(\pi(i)) \\ (\pi,i) \models_{k} f \wedge g & \text{iff} & (\pi,i) \models_{k} f \text{ and } (\pi,i) \models_{k} g \\ (\pi,i) \models_{k} f \vee g & \text{iff} & (\pi,i) \models_{k} f \text{ or } (\pi,i) \models_{k} g \\ (\pi,i) \models_{k} \Box f & \text{iff} & false \\ (\pi,i) \models_{k} \Diamond f & \text{iff} & \exists j \in [i,k].(\pi,j) \models_{k} f \\ (\pi,i) \models_{k} \cap f & \text{iff} & i < k \text{ and } (\pi,i+1) \models_{k} f \\ (\pi,i) \models_{k} f \mathcal{U} g & \text{iff} & \exists j \in [i,k].((\pi,j) \models_{k} g \text{ and } \forall n \in [i,j].(\pi,n) \models_{k} f) \\ (\pi,i) \models_{k} f \mathcal{R} g & \text{iff} & \exists j \in [i,k].((\pi,j) \models_{k} f \text{ and } \forall n \in [i,j].(\pi,n) \models_{k} g) \end{array}$$

• Note: $(\pi, i) \models_k f$ is written as $\pi \models_k^i f$ in the paper.

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Bounded Semantics without a Loop (cont.)



- Note that the bounded semantics without a loop imply that the following two dualities no longer hold:

 - the duality of U and \mathcal{R} (\neg (f U g) = (\neg f) \mathcal{R} (\neg g)).

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Lemma

Lemma

Let f be an LTL formula and M a Kripke structure. If $M \models \mathbf{E}$ f then there exists $k \in \mathbb{N}$ with $M \models_k \mathbf{E}$ f.

Let h be an LTL formula and π a path, then $\pi \models_k h \Rightarrow \pi \models h$.

Theorem

Let f be an LTL formula and M a Kripke structure. Then $M \models \mathbf{E}$ f iff there exists $k \in \mathbb{N}$ with $M \models_k \mathbf{E}$ f.

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Let *h* be an LTL formula and π a path, then $\pi \models_k h \Rightarrow \pi \models h$.

? Case 1: π is a *k*-loop.

The conclusion follows by the definition.

• Case 2: π is not a loop.

Prove by induction over the structure of f and $i \le k$ the stronger property $\pi \models_k^i h \Rightarrow \pi^i \models h$.

Proof of Lemma 1 (cont.)



$$\begin{aligned} \pi \models_{k}^{i} f \mathcal{R} g \\ \Leftrightarrow \quad \exists j \in [i,k]. (\pi \models_{k}^{j} f \text{ and } \forall n \in [i,j].\pi \models_{k}^{n} g) \\ \Rightarrow \quad \exists j \in [i,k]. (\pi^{j} \models f \text{ and } \forall n \in [i,j].\pi^{n} \models g) \\ \Rightarrow \quad \exists j \in [i,\infty]. (\pi^{j} \models f \text{ and } \forall n \in [i,j].\pi^{n} \models g) \\ \Rightarrow \quad \exists j' \in [0,\infty). (\pi^{i+j'} \models f \text{ and } \forall n' \in [0,j'].\pi^{i+n'} \models g) \\ (\text{with } j' = j - i \text{ and } n' = n - i) \\ \Rightarrow \quad \exists j \in [0,\infty). [(\pi^{i})^{j} \models f \text{ and } \forall n \in [0,j]. (\pi^{i})^{n} \models g] \\ \Rightarrow \quad \forall n \in [0,\infty). [(\pi^{i})^{n} \models g \text{ or } \exists j \in [0,n). (\pi^{i})^{j} \models f] \\ (\text{see next slide}) \\ \Rightarrow \quad \pi^{i} \models f \mathcal{R} g \end{aligned}$$

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Proof of Lemma 1 (cont.)



$\exists m[\pi^m \models f \text{ and } \forall l, l \leq m.\pi^l \models g] \Rightarrow \forall n[\pi^n \models g \text{ or } \exists j, j < n.\pi^j \models f]$

- Solution Section 8.2. Solution $\pi^{\prime\prime}\models g$ for all I with $I\leq m$.
- 😚 Case 1: *n > m*.
 - Based on the assumption, there exists j < n such that $\pi^j \models f$ (choose j = m).
- Solution Gaussian Gaussia

Proof of Lemma 2



Let f be an LTL formula and M a Kripke structure. If $M \models \mathbf{E} f$ then there exists $k \in \mathbb{N}$ with $M \models_k \mathbf{E} f$.

- If f is satisfiable in M, then there exists a path in the product structure of M and the tableau of f that starts with an initial state and ends with a cycle in the strongly connected component of fair states.
- This path can be chosen to be a k-loop with k bounded by $|S| \cdot 2^{|f|}$ which is the size of the product structure.
- If we project this path onto its first component, the original Kripke structure, then we get a path π that is a k-loop and in addition fulfills $\pi \models f$.
- 😚 By definition of the bounded semantics this also implies $\pi \models_k f$.

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- Given a Kripke structure M, an LTL formula f, and a bound k, we will construct a propositional formula [[M, f]]_k.
- The bounded model checking problem can be reduced in polynomial time to propositional satisfiability.
 - The size of $[\![M, f]\!]_k$ is polynomial in the size of f if common sub-formulae are shared.
 - it is quadratic in k and linear in the size of the propositional formulae for T, I, and the $p \in A$.

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Unfolding the Transition Relation



• For a Kripke structure M and $k \in \mathbb{N}$,

$$\llbracket M \rrbracket_k \triangleq I(s_0) \land \bigwedge_{i=0}^{k-1} T(s_i, s_{i+1})$$

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Trans. of an LTL formula without a Loop



• For an LTL formula f and $k, i \in \mathbb{N}$, with $i \leq k$,

$$\begin{split} \llbracket p \rrbracket_{k}^{i} &\triangleq p(s_{i}) \\ \llbracket \neg p \rrbracket_{k}^{i} &\triangleq \neg p(s_{i}) \\ \llbracket f \land g \rrbracket_{k}^{i} &\triangleq \llbracket f \rrbracket_{k}^{i} \land \llbracket g \rrbracket_{k}^{i} \\ \llbracket f \lor g \rrbracket_{k}^{i} &\triangleq \llbracket f \rrbracket_{k}^{i} \lor \llbracket g \rrbracket_{k}^{i} \\ \llbracket f \lor g \rrbracket_{k}^{i} &\triangleq \llbracket f \rrbracket_{k}^{i} \lor \llbracket g \rrbracket_{k}^{i} \\ \llbracket \Box f \rrbracket_{k}^{i} &\triangleq false \\ \llbracket \diamond f \rrbracket_{k}^{i} &\triangleq \bigvee_{j=i}^{k} \llbracket f \rrbracket_{k}^{j} \\ \llbracket \bigcirc f \rrbracket_{k}^{i} &\triangleq if i < k \text{ then } \llbracket f \rrbracket_{k}^{i+1} \text{ else } false \\ \llbracket f \ \mathcal{U} \ g \rrbracket_{k}^{i} &\triangleq \bigvee_{j=i}^{k} [\llbracket g \rrbracket_{k}^{j} \land \bigwedge_{n=i}^{j-1} \llbracket f \rrbracket_{k}^{n}) \\ \llbracket f \ \mathcal{R} \ g \rrbracket_{k}^{i} &\triangleq \bigvee_{j=i}^{k} (\llbracket f \rrbracket_{k}^{j} \land \bigwedge_{n=i}^{j-1} \llbracket g \rrbracket_{k}^{n}) \end{split}$$

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Trans. of an LTL formula for a Loop



• For an LTL formula f and $k, l, i \in \mathbb{N}$, with $l, i \leq k$,

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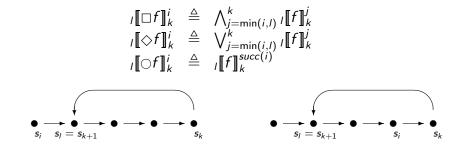
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Trans. of an LTL formula for a Loop





• Let $k, I, i \in \mathbb{N}$, with $I, i \leq k$.

$$succ(i) \triangleq \left\{ \begin{array}{ll} i+1 & {
m for } i < k \\ l & {
m for } i = k \end{array} \right.$$

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Trans. of an LTL formula for a Loop (cont.)



$$\begin{bmatrix} f \ \mathcal{U} \ g \end{bmatrix}_{k}^{i} \triangleq \bigvee_{j=i}^{k} ({}_{l}\llbracket g \rrbracket_{k}^{j} \land \bigwedge_{n=i}^{j-1} {}_{l}\llbracket f \rrbracket_{k}^{n}) \lor$$
$$\bigvee_{j=l}^{i-1} ({}_{l}\llbracket g \rrbracket_{k}^{j} \land \bigwedge_{n=i}^{k} {}_{l}\llbracket f \rrbracket_{k}^{n} \land \bigwedge_{n=l}^{j-1} {}_{l}\llbracket f \rrbracket_{k}^{n})$$

$$\begin{bmatrix} f \ \mathcal{R} \ g \end{bmatrix}_{k}^{i} \triangleq \bigwedge_{j=\min(i,l)}^{k} \llbracket g \rrbracket_{k}^{j} \lor \\ \bigvee_{j=i}^{k} (\llbracket f \rrbracket_{k}^{j} \land \bigwedge_{n=i}^{j} \llbracket g \rrbracket_{k}^{n}) \lor \\ \bigvee_{j=l}^{i-1} (\llbracket f \rrbracket_{k}^{j} \land \bigwedge_{n=i}^{k} \llbracket g \rrbracket_{k}^{n} \land \bigwedge_{n=l}^{j} \llbracket g \rrbracket_{k}^{n})$$



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The loop condition L_k is used to distinguish paths with bound k which are loops or not loops.

♦ For
$$k, l \in \mathbb{N}$$
, let

$$L_k \triangleq T(s_k, s_l)$$

$$L_k \triangleq \bigvee_{l=0}^k L_k.$$

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General Translation



Solution f be an LTL formula, M a Kripke structure, and $k \in \mathbb{N}$.

$$\llbracket M, f \rrbracket_k \triangleq \llbracket M \rrbracket_k \land ((\neg L_k \land \llbracket f \rrbracket_k^0) \lor (\bigvee_{l=0}^k ({}_l L_k \land {}_l \llbracket f \rrbracket_k^0)))$$

Note: is the term $\neg L_k$ redundant?

Theorem

 $\llbracket M, f \rrbracket_k$ is satisfiable iff $M \models_k \mathbf{E} f$.

Corollary

 $M \models \mathbf{A} \neg f$ iff $\llbracket M, f \rrbracket_k$ is unsatisfiable for all $k \in \mathbb{N}$.

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Bounds for LTL



- S LTL model checking is known to be PSPACE-complete.
- A polynomial bound on k with respect to the size of M and f for which $M \models_k \mathbf{E} f \Leftrightarrow M \models \mathbf{E} f$ is unlikely to be found.

Theorem

Given an LTL formula f and a Kripke structure M, let |M| be the number of states in M, then $M \models \mathbf{E}$ f iff there exists $k \leq |M| \times 2^{|f|}$ with $M \models_k \mathbf{E}$ f.

- For this subset of LTL formulae, there exists a bound on k linear in the number of states and the size of the formula.

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Bounds for LTL (cont.)



Definition (Loop Diameter)

A Kripke structure is lasso shaped if every path p starting from an initial state is of the form $u_p v_p^{\omega}$, where u_p and v_p are finite sequences of length less or equal to u and v, respectively. The loop diameter of M is defined as (u, v).

Theorem

Given an LTL formula f and a lasso-shaped Kripke structure M, let the loop diameter of M be (u, v), then $M \models \mathbf{E}$ f iff there exists $k \le u + v$ with $M \models_k \mathbf{E}$ f.

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Part II:

Bounded Model Checking for LTL with Past

Note: (k, l)-loop here corresponds to (k - 1, l)-loop in Part I. For easy cross-referencing with the original paper, we have not attempted to unify the notion.

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Propositional Temporal Logic



The full propositional temporal logic (PTL) is LTL with past operators.

 $\begin{array}{lll} (\pi,i)\models \odot f & \text{iff} & i>0 \text{ and } (\pi,i-1)\models f \\ (\pi,i)\models \odot f & \text{iff} & i=0 \text{ or } (\pi,i-1)\models f \\ (\pi,i)\models \otimes f & \text{iff} & \exists j,j\leq i.(\pi,j)\models f \\ (\pi,i)\models \exists f & \text{iff} & \forall j,j\leq i.(\pi,j)\models f \\ (\pi,i)\models f \mathcal{S} g & \text{iff} & \exists j,j\leq i.((\pi,j)\models g \text{ and } \forall k,j< k\leq i.(\pi,k)\models f) \\ (\pi,i)\models f \mathcal{T} g & \text{iff} & \forall j,j\leq i.((\pi,j)\models g \text{ or } \exists k,j< k\leq i.(\pi,k)\models f) \end{array}$

Every PTL formula can be converted into the negation normal form.

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Extend the Translation without Loops



Solution
$$k, i \in \mathbb{N}$$
 with $i \leq k$.

$$\begin{split} \llbracket \odot f \rrbracket_{k}^{i} & \triangleq \begin{cases} false & i = 0 \\ \llbracket f \rrbracket_{k}^{i-1} & i > 0 \\ \end{bmatrix} \\ \llbracket \odot f \rrbracket_{k}^{i} & \triangleq \begin{cases} false & i = 0 \\ \llbracket f \rrbracket_{k}^{i-1} & i > 0 \\ \llbracket f \rrbracket_{k}^{i-1} & i > 0 \\ \end{bmatrix} \\ \llbracket \odot f \rrbracket_{k}^{i} & \triangleq \bigvee_{j=0}^{i} \llbracket f \rrbracket_{k}^{j} \\ \llbracket \Box f \rrbracket_{k}^{i} & \triangleq \bigwedge_{j=0}^{i} \llbracket f \rrbracket_{k}^{j} \\ \llbracket f \ S \ g \rrbracket_{k}^{i} & \triangleq \bigvee_{j=0}^{i} (\llbracket g \rrbracket_{k}^{j} \land \bigwedge_{n=j+1}^{i} \llbracket f \rrbracket_{k}^{n}) \\ \llbracket f \ T \ g \rrbracket_{k}^{i} & \triangleq \bigwedge_{j=0}^{i} (\llbracket g \rrbracket_{k}^{j} \lor \bigvee_{n=j+1}^{i} \llbracket f \rrbracket_{k}^{n}) \end{split}$$

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Extend the Translation with Loops



- 😚 The extension is not straightforward.
- For example, consider the path 01(2345)^ω which can be seen as a (6, 2)-loop.
 - In the future case, the encoding of a specification is based on the idea that, for every time in the encoding, exactly one successor time exists.
 - Past formulae do not enjoy the above property.

The predecessor of 2 may be 1 or 5.



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The Solution: Intuition



- The formula $\Diamond(x = 2 \land \Diamond(x = 3 \land \Diamond(x = 4 \land (\Diamond(x = 5)))))$ is true in all the occurrences of x = 2 after the fourth.
- The key idea is that every formula has a finite discriminating power for events in the past.
- When evaluated sufficiently far from the origin of time, a formula becomes unable to distinguish its past sequence from infinitely many other past sequences with a "similar" behavior.
- The idea is then to collapse the undistinguishable versions of the past together into the same equivalence class.

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So The past temporal horizon (PTH) $\tau_{\pi}(f)$ of a PTL formula f with respect to a (k, l)-loop π (with period p = k - l) is the smallest value $n \in \mathbb{N}$ such that

$$\forall i, l \leq i < k.((\pi, i + np) \models f \text{ iff } (\forall n' > n.(\pi, i + n'p) \models f)).$$

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PTH of a PTL Formula



The PTH $\tau(f)$ of a PTL formula f is defined as $\tau(f) \triangleq \max_{\tau \in \Pi} \tau_{\pi}(f)$ where Π is the set of all the paths which are (k, I)-loops for some $k > I \ge 0$.

Theorem

Let f and g be PTL formulae. Then, it holds that:

•
$$\tau(p) = 0$$
, when $p \in A$ and $\tau(f) = \tau(\neg f)$;
• $\tau(\circ f) \leq \tau(f)$, when $\circ \in \{\bigcirc, \diamondsuit, \square\}$;
• $\tau(\circ f) \leq \tau(f) + 1$, when $\circ \in \{\ominus, \ominus, \diamondsuit, \ominus\}$;
• $\tau(f \circ g) \leq \max(\tau(f), \tau(g))$, when $\circ \in \{\land, \lor, \mathcal{U}, \mathcal{R}\}$;
• $\tau(f \circ g) \leq \max(\tau(f), \tau(g)) + 1$, when $\circ \in \{S, \mathcal{T}\}$;

The PTH of a PTL formula is bounded by its structure regardless of the particular path π .

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Borders and Intervals



😚 We call

- ♦ **LB**(*n*) \triangleq *l* + *np* the *n*-th left border of *π*,
- ***** $\mathsf{RB}(n) \triangleq k + np$ the *n*-th right border of π , and
- * the interval $M(n) \triangleq [0, \mathbf{RB}(n))$ the *n*-th main domain of a (k, l)-loop.

😚 We call

LB(f) \u2295 **LB**(\u03c6(f)) the left border of f, **RB**(f) \u2295 **RB**(\u03c6(f)) the right border of f, and *M*(f) \u2295 *M*(\u03c6(f)) the main domain of f.

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Borders and Intervals (cont.)





LB(0) = 2
RB(0) = 6
LB(1) = 6
RB(1) = 10

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Projection of Points



• Let $i \in \mathbb{N}$.

The projection of the point i in the n-th main domain of a (k, l)-loop is ρ_n(i), defined as

$$ho_n(i) riangleq \left\{ egin{array}{cc} i & i < {f RB}(n) \
ho_n(i-p) & {
m otherwise} \end{array}
ight.$$

The projection of the point *i* onto the main domain of *f* is defined as $\rho_f(i) \triangleq \rho_{\tau(f)}(i)$.

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Projection of Intervals



The projection of the interval [a, b) onto the main domain of f is defined as $\rho_f([a, b)) \triangleq \rho_{\tau(f)}([a, b))$.

Lemma

For an open interval [a, b),

$$\rho_n([a,b)) = \begin{cases} \emptyset & \text{if } a = b, \text{ else} \\ [a,b) & \text{if } b < \mathbf{RB}(n), \text{ else} \\ [\min(a, \mathbf{LB}(n)), \mathbf{RB}(n)) & \text{if } b - a \ge p, \text{ else} \\ [\rho_n(a), \rho_n(b)) & \text{if } \rho_n(a) < \rho_n(b), \text{ else} \\ [\rho_n(a), \mathbf{RB}(n)) \cup [\mathbf{LB}(n), \rho_n(b)) \end{cases}$$

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Extended Projection of Intervals



- An extended intervals is of the form [a, b) where b is possibly less than a (or even it is equal to ∞).
- Let [a, b) be an extended interval.
- The extended projection of [a, b) onto the n-th main domain of a (k, l)-loop is defined as follows

$$\rho_n^*([a, b)) \triangleq \begin{cases} \rho_n^*([a, \max(a, \mathbf{RB}(n)) + p)) & b = \infty \\ \rho_n^*([a, b + p)) & b < a \\ \rho_n^*([a, b)) & \text{otherwise} \end{cases}$$

• As before, $\rho_f^*([a, b)) \triangleq \rho_{\tau(f)}^*([a, b))$.

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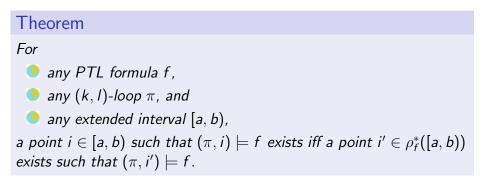
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Equivalent Counterparts





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Extend the Translation with Loops



The translation of a PTL formula on a (k, l)-loop π at time point i (with k, l, i ∈ N and 0 ≤ l < k) is a propositional formula inductively defined as follows.

$$I\llbracket p \rrbracket_{k}^{i} \triangleq p^{\rho_{0}(i)}$$

$$I\llbracket \neq p \rrbracket_{k}^{i} \triangleq \neq p^{\rho_{0}(i)}$$

$$I\llbracket f \land g \rrbracket_{k}^{i} \triangleq I\llbracket f \rrbracket_{k}^{\rho_{f}(i)} \land I\llbracket g \rrbracket_{k}^{\rho_{g}(i)}$$

$$I\llbracket f \lor g \rrbracket_{k}^{i} \triangleq I\llbracket f \rrbracket_{k}^{\rho_{f}(i)} \lor I\llbracket g \rrbracket_{k}^{\rho_{g}(i)}$$

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Extend the Translation with Loops (cont.)



$$\begin{split} & {}_{l} [\diamondsuit f]]_{k}^{i} \triangleq \bigvee_{j \in \rho_{f}^{*}([i,\infty))} {}_{l} [f]]_{k}^{j} \\ & {}_{l} [\Box f]]_{k}^{i} \triangleq \bigwedge_{j \in \rho_{g}^{*}([i,\infty))} {}_{l} [f]]_{k}^{j} \\ & {}_{l} [f \mathcal{U} g]]_{k}^{i} \triangleq \bigvee_{j \in \rho_{g}^{*}([i,\infty))} {}_{l} [f]]_{k}^{j} \land \bigwedge_{n \in \rho_{f}^{*}([i,j))} {}_{l} [f]]_{k}^{n} \\ & {}_{l} [f \mathcal{R} g]]_{k}^{i} \triangleq \bigwedge_{j \in \rho_{g}^{*}([i,\infty))} {}_{l} [g]]_{k}^{j} \lor \bigvee_{n \in \rho_{f}^{*}([i,j))} {}_{l} [f]]_{k}^{n} \\ & {}_{l} [\bigcirc f]]_{k}^{i} \triangleq i > 0 \land {}_{l} [f]]_{k}^{\rho_{f}(i-1)} \\ & {}_{l} [\bigcirc f]]_{k}^{i} \triangleq i = 0 \lor {}_{l} [f]]_{k}^{\rho_{f}(i-1)} \\ & {}_{l} [\bigcirc f]]_{k}^{i} \triangleq \bigvee_{j \in \rho_{f}^{*}([0,i])} {}_{l} [f]]_{k}^{j} \\ & {}_{l} [\boxdot f]]_{k}^{i} \triangleq \bigvee_{j \in \rho_{f}^{*}([0,i])} {}_{l} [f]]_{k}^{j} \\ & {}_{l} [f \mathcal{S} g]]_{k}^{i} \triangleq \bigwedge_{j \in \rho_{g}^{*}([0,i])} {}_{l} [f]]_{k}^{j} \lor \bigvee_{n \in \rho_{f}^{*}((j,i])} {}_{l} [f]]_{k}^{n}) \\ & {}_{l} [f \mathcal{T} g]]_{k}^{i} \triangleq \bigwedge_{j \in \rho_{g}^{*}([0,i])} {}_{l} [g]]_{k}^{j} \lor \bigvee_{n \in \rho_{f}^{*}((j,i])} {}_{l} [f]]_{k}^{n}) \end{split}$$

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Correctness of the Translation



Theorem

For any PTL formula f, a(k, I)-loop path π in M such that $\pi \models f$ exists iff $\llbracket M \rrbracket_k \wedge {}_I L_k \wedge {}_I \llbracket f \rrbracket_k^0$ is satisfiable.

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